

Math 1080: Spring 2010
Homework #10 (due April 15)

Problem 1:

Let \mathbf{Q} and \mathbf{R} be the QR factors of a symmetric tridiagonal matrix \mathbf{H} . Show that the product $\mathbf{K} = \mathbf{RQ}$ is again a symmetric tridiagonal matrix.

(Hint: Prove the symmetry of \mathbf{K} . Show that \mathbf{Q} has Hessenberg form and that the product of an upper triangular matrix and a Hessenberg matrix is again a Hessenberg matrix. Then use the symmetry of \mathbf{K} .)

Problem 2:

Reduce the following matrix to Hessenberg form.

$$\mathbf{A} = \begin{bmatrix} 3 & 7 & -2 & -8 \\ -2 & 1 & 1 & 4 \\ 4 & 9 & 0 & 0 \\ 4 & -4 & -4 & 2 \end{bmatrix}$$

Computer Assignment 7:

- a) Write a MATLAB function `[Q,L]=qralgshift(A,eps)` that computes the eigenvalues and eigenvectors of a square, symmetric $m \times m$ matrix \mathbf{A} using QR algorithm with shift. The output variables are the $m \times m$ orthogonal matrix \mathbf{Q} whose columns are the eigenvectors of \mathbf{A} and $m \times m$ matrix \mathbf{L} that has the corresponding eigenvalues of \mathbf{A} on the main diagonal. The program should terminate iteration when the norm of the offdiagonal elements of $\mathbf{A}^{(k)}$, i.e., $\text{norm}(\mathbf{A} - \text{diag}(\text{diag}(\mathbf{A})))$, is smaller than 10^{-6} .
- b) Write a MATLAB function `[Q,H]=hessenberg(A)` that computes the Hessenberg form of $m \times m$ matrix \mathbf{A} . The output variables are $m \times m$ orthogonal matrix \mathbf{Q} and $m \times m$ matrix \mathbf{H} similar to \mathbf{A} that is in Hessenberg form.
- c) Calculate the eigenvalues and eigenvectors of using (1) `qralgshift` algorithm only and (2) a combination of `hessenberg` and `qralgshift`.

$$\mathbf{A} = \begin{bmatrix} 3 & -2 & 12 & -9 & -6 & -9 \\ -2 & 3 & 1 & 8 & -1 & -1 \\ 12 & 1 & -9 & -3 & -3 & -11 \\ -9 & 8 & -3 & 4 & 4 & 17 \\ -6 & -1 & -3 & 4 & 15 & -3 \\ -9 & -1 & -11 & 17 & -3 & 7 \end{bmatrix}$$

Record the number of iterations needed to achieve the desired accuracy. Compare the two methods.